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Adaptive Kinematic Control
of Mobile Robot based on
Neural Networks
Case Study: National Instruments Starter Kit 2 (DANI
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Condition: New. Publisher/Verlag: LAP Lambert Academic Publishing | Case Study: National Instruments Starter Kit 2 (DANI Robot) | The applications of mobile robots have grown significantly during the last few years due to the fast development in sensors and microprocessors systems. These applications include material handling, hospital services, military applications . etc. The need for a precise motion control becomes very crucial in order to support such applications. The adaptive motion control for mobile robot is one of the important...

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